



## Introduction

The resulting Coarse operator is a nearest-neighbor operator Adaptive Aggregation based multi-grid (MG) methods [1,2,3] are becoming the standard for solvers in both the propagator similar in structure to the fine operator: calculation and recently even in the gauge generation parts of  $\delta_{x,x+\hat{\mu}}$ Lattice QCD calculations with Wilson Clover Fermions. The system solved is A x = b, where A is the Dirac operator

## **Multi-Grid Solvers**

### V-Cycle & K-Cycle

MG aims to reduce the short wavelength (UV) modes on a fine grid using a Smoother (S). The error due to the longer wavelength modes is solved on a coarser grid by solving with a coarsened operator (A<sup>-1</sup><sub>c</sub>). A typical cycle is the V-cycle:



The error is reduced as (e.g. [2]):

# $e' \leftarrow (I - SA)^k (1 - PA_c^{-1}RA)(1 - SA)^j e_0$

#### **Near Null Space Block Aggregation**

Low modes of the A are `self similar' on cubic-blocks of the lattice due to local coherence (weak approximation). Hence one way to define R is to aggregate the fine degrees of freedom over cubic blocks with near null-space vectors produced in a setup phase



Restriction: Aggregation over sites, colors, chiral spin components.

Fine Grid d.o.f : V<sub>f</sub> x N<sub>spin</sub> x N<sub>color</sub>

Coarse Grid d.o.f : V<sub>c</sub> x N<sub>chiral</sub> x N<sub>null</sub>

# MG Proto: A Multigrid Solver for x86 multicore Systems

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## **Coarse Operator**

$$A_c(x) = X_0(x) + \sum_{\mu=1..8} X_{\mu}(x) \, \delta$$

Where  $X_0(x)$  and  $X_{\mu}(x)$  are matrices of dimension  $N_{null}xN_{chiral}$ .

#### **SIMD** for matrix-vector operation

Applying Ac consists of 9 matrix vector multiplications. We restrict to N<sub>null</sub> being a multiple of 8 and vectorize using AVX512 intrinsics:



### **Nested Parallelism for Aggregation**



Nsites in block

Aggregations for restriction and prolongation permit nested parallelism through a) parallelism over blocks and b) within blocks. **Parallelism within blocks** may be desirable if there are very few coarse sites (e.g. a coarse level with 16 sites, on a KNL system)



Utilizing threading within the site was only really beneficial when there was not enough parallelism via sites (V=4<sup>4</sup> and V=4<sup>3</sup>x8 cases). In this instance benefit was visible when manual (man) implementation of nested parallelism was employed, rather than through explicit OpenMP nested (exp) parallelism. In these (man) cases serial reductions (ser. red.) in the blocks proved more efficient than parallel ones. [4]









## **Other optimizations**

**Our MGProto implementation uses the QPhiX library** for threading and vectorization on the fine grid. In addition we have implemented Schur Decomposition based even-odd preconditioning In all the solvers used on all MG levels.

## **Performance Results**



Performance results and strong scaling on Stampede 2 using Skylake (SKX) nodes Multigrid provides approximately an 8x reduction in solve time than the fastest available, mxsed precision BiCGStab solver from the QPhiX library. Similar performance improvements are also visible on KNL systems, e.g. Cori and Theta

# **Conclusions & Outlook**

Our implementation delivers a roughly 8x improvement over our best previous solver for KNL and Skylake systems. Coincidentally, 64 nodes of Stampede performs similarly to 64 nodes of Titan in 2016 using QUDA-MG. This work opens Cori and Theta for propagator calculations and for gauge generation using multi-grid in the future. It also serves as a basis for performance portability explorations.

# References Acknowledgement



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